

# Improved Analysis of UCRL2 with Empirical Bernstein Inequality

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## Abstract

We consider the problem of exploration-exploitation in communicating Markov Decision Processes. We provide an analysis of UCRL2 with Empirical Bernstein inequalities (UCRL2B). For any MDP with  $S$  states,  $A$  actions,  $\Gamma \leq S$  next states and diameter  $D$ , the regret of UCRL2B is bounded as  $\tilde{O}(\sqrt{D\Gamma SAT})$ .

## 1 Introduction

Jaksch et al. (2010) introduced the reinforcement learning algorithm UCRL2 and proved a regret bound of order  $\tilde{O}(DS\sqrt{AT})$  for any communicating MDP with  $S$  states,  $A$  actions and diameter  $D$ . UCRL2 used Hoeffding inequalities to build an uncertainty set around rewards and transitions. (Fruit et al., 2018) exploited empirical Bernstein inequalities to prove a regret bound of  $\tilde{O}(D\sqrt{\Gamma SAT})$  where  $\Gamma := \max_{s,a} \Gamma(s,a) \leq S$  is the maximum number of possible next states. In this document, we show that we can improve the analysis of UCRL2 with empirical Bernstein bound (UCRL2B) and we show a regret bound of  $\tilde{O}(\sqrt{D\Gamma SAT})$ . This document is intended as a support to our tutorial at the 30th International Conference on Algorithmic Learning Theory (ALT 2019). For a more detailed analysis, please refer to (Fruit, 2019).

## 2 Preliminaries

We consider a *communicating* MDP (Puterman, 1994, Sec. 8.3)  $M = (\mathcal{S}, \mathcal{A}, p, r)$  with state space  $\mathcal{S}$  and action space  $\mathcal{A}$ . Every state-action pair  $(s, a)$  is characterized by a reward distribution with mean  $r(s, a)$  and support in  $[0, r_{\max}]$ , and a transition distribution  $p(\cdot|s, a)$  over next states. We denote by  $S = |\mathcal{S}|$  and  $A = |\mathcal{A}|$  the number of states and action, by  $\Gamma(s, a) = \|p(\cdot|s, a)\|_0$  the number of states reachable by selecting action  $a$  in state  $s$ , and by  $\Gamma = \max_{s,a} \Gamma(s, a)$  its maximum. A stationary Markov randomized policy  $\pi : \mathcal{S} \rightarrow P(\mathcal{A})$  maps states to distributions over actions. The set of stationary randomized (resp. deterministic) policies is denoted by  $\Pi^{\text{SR}}$  (resp.  $\Pi^{\text{SD}}$ ). Any policy  $\pi \in \Pi^{\text{SR}}$  has an associated *long-term average reward* (or gain) and a *bias function* defined as

$$g^\pi(s) := \lim_{T \rightarrow +\infty} \mathbb{E}_s^\pi \left[ \frac{1}{T} \sum_{t=1}^T r(s_t, a_t) \right] \quad \text{and} \quad h^\pi(s) := C\text{-}\lim_{T \rightarrow +\infty} \mathbb{E}_s^\pi \left[ \sum_{t=1}^T (r(s_t, a_t) - g^\pi(s_t)) \right],$$

where  $\mathbb{E}_s^\pi$  denotes the expectation over trajectories generated starting from  $s_1 = s$  with  $a_t \sim \pi(s_t)$ . The bias  $h^\pi(s)$  measures the expected total difference between the reward and the stationary reward in *Cesaro-limit* (denoted by  $C\text{-lim}$ ). Accordingly, the difference of bias  $h^\pi(s) - h^\pi(s')$  quantifies the (dis-)advantage of starting in state  $s$  rather than  $s'$ . We denote by  $sp(h^\pi) := \max_s h^\pi(s) - \min_s h^\pi(s)$  the *span* of the bias function. In weakly communicating MDPs, any optimal policy  $\pi^* \in \arg \max_\pi g^\pi(s)$  has *constant* gain, i.e.,  $g^{\pi^*}(s) = g^*$  for all  $s \in \mathcal{S}$ . Moreover, there exists a policy  $\pi^* \in \arg \max_\pi g^\pi(s)$  for which  $(g^*, h^*) = (g^{\pi^*}, h^{\pi^*})$  satisfy the *optimality equation*,

$$\forall s \in \mathcal{S}, \quad h^*(s) + g^* = Lh^*(s) := \max_{a \in \mathcal{A}} \{r(s, a) + p(\cdot|s, a)^\top h^*\}, \quad (1)$$

where  $L$  is the *optimal* Bellman operator. Finally,  $D = \max_{s \neq s'} \{\tau(s \rightarrow s')\}$  denotes the diameter of  $M$ , where  $\tau(s \rightarrow s')$  is the minimal expected number of steps needed to reach  $s'$  from  $s$ .

<p><b>Input:</b> Confidence <math>\delta \in ]0, 1[</math>, <math>r_{\max}</math>, <math>\mathcal{S}</math>, <math>\mathcal{A}</math></p> <p><b>Initialization:</b> Set <math>t := 1</math> and observe <math>s_1</math> and for any <math>(s, a, s') \in \mathcal{S} \times \mathcal{A} \times \mathcal{S}</math>: <math>N_1(s, a) = 0</math>, <math>\hat{p}_1(s' s, a) = 0</math>, <math>\hat{r}_1(s, a) = 0</math>, <math>\hat{\sigma}_{p,1}^2(s' s, a) = 0</math>, <math>\hat{\sigma}_{r,1}^2(s, a) = 0</math></p> <p><b>For</b> episodes <math>k = 1, 2, \dots</math> <b>do</b></p> <ol style="list-style-type: none"> <li>1. Set <math>t_k \leftarrow t</math> and episode counters <math>\nu_k(s, a) \leftarrow 0</math></li> <li>2. Compute the upper-confidence bounds (Eq. 5 and 6) and the extended MDP <math>\mathcal{M}_k</math> as in Eq. 2</li> <li>3. Compute an <math>r_{\max}/t_k</math>-approximation <math>\pi_k</math> of Eq. 7: <math>(g_k, h_k, \pi_k) = \text{EVI}(\mathcal{L}_\alpha^k, \mathcal{G}_\alpha^k, \frac{r_{\max}}{t_k}, 0, s_1)</math></li> <li>4. Sample action <math>a_t \sim \pi_k(\cdot s_t)</math></li> <li>5. <b>While</b> <math>t_k = t</math> <b>or</b> <math>\nu_k(s_t, a_t) \leq \max\{1, N_k(s_t, a_t)\}</math> <b>do</b> <ol style="list-style-type: none"> <li>(a) Execute <math>a_t</math>, obtain reward <math>r_t</math>, and observe <math>s_{t+1}</math></li> <li>(b) Sample action <math>a_{t+1} \sim \pi_k(\cdot s_{t+1})</math></li> <li>(c) Set <math>\nu_k(s_t, a_t) \leftarrow \nu_k(s_t, a_t) + 1</math> and set <math>t \leftarrow t + 1</math></li> </ol> </li> <li>6. Set <math>N_{k+1}(s, a) \leftarrow N_k(s, a) + \nu_k(s, a)</math></li> <li>7. Update statistics (i.e., <math>\hat{p}_{k+1}, \hat{r}_{k+1}, \hat{\sigma}_{p,k+1}^2</math> and <math>\hat{\sigma}_{r,k+1}^2</math>)</li> </ol>
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Figure 1: UCRL2B algorithm.

**Learning Problem.** Let  $M^*$  be the true MDP. We consider the learning problem where  $\mathcal{S}$ ,  $\mathcal{A}$  and  $r_{\max}$  are *known*, while rewards  $r$  and dynamics  $p$  are *unknown* and need to be estimated *on-line*. We evaluate the performance of a learning algorithm  $\mathfrak{A}$  after  $T$  time steps by its cumulative *regret*  $\Delta(\mathfrak{A}, T) = \sum_{t=1}^T (g^* - r_t(s_t, a_t))$ .

### 3 UCRL2B

UCRL2B is a variant of UCRL2 (Jaksch et al., 2010) that construct confidence intervals based on the empirical Bernstein inequality (Audibert et al., 2007) rather than Hoeffding’s inequality. As UCRL2, UCRL2B proceeds through episodes  $k = 1, 2, \dots$ . At the beginning of each episode  $k$ , UCRL computes a set of plausible MDPs defined as

$$\mathcal{M}_k = \left\{ M = \langle \mathcal{S}, \mathcal{A}, \tilde{r}, \tilde{p} \rangle : \tilde{r}(s, a) \in B_r^k(s, a), \tilde{p}(s'|s, a) \in B_p^k(s, a, s'), \sum_{s'} \tilde{p}(s'|s, a) = 1 \right\}, \quad (2)$$

where  $B_r^k$  and  $B_p^k$  are high-probability confidence intervals on the rewards and transition probabilities of the true MDP  $M^*$ , which guarantees that (see App. B.2)

$$\mathbb{P}(\exists k \geq 1, \text{ s.t. } M^* \notin \mathcal{M}_k) \leq \frac{\delta}{3}.$$

As mentioned, we use confidence intervals constructed using empirical Bernstein’s inequality (Audibert et al., 2009, Thm. 1)

$$\beta_{p,k}^{s a s'} := 2 \sqrt{\frac{\hat{\sigma}_{p,k}^2(s'|s, a)}{N_k^+(s, a)} \ln \left( \frac{6S A N_k^+(s, a)}{\delta} \right)} + \frac{6 \ln \left( \frac{6S A N_k^+(s, a)}{\delta} \right)}{N_k^+(s, a)} \quad (3)$$

$$\beta_{r,k}^{s a} := 2 \sqrt{\frac{\hat{\sigma}_{r,k}^2(s, a)}{N_k^+(s, a)} \ln \left( \frac{6S A N_k^+(s, a)}{\delta} \right)} + \frac{6r_{\max} \ln \left( \frac{6S A N_k^+(s, a)}{\delta} \right)}{N_k^+(s, a)} \quad (4)$$

where  $N_k(s, a)$  is the number of visits in  $(s, a)$  before episode  $k$ ,  $N_k^+(s, a) = \max\{1, N_k(s, a)\}$ ,  $\hat{\sigma}_{p,k}^2$  and  $\hat{\sigma}_{r,k}^2$  are the population variance of transition and reward function at episode  $k$ . We define by  $\hat{r}_k$  and  $\hat{p}_k$  the empirical average of rewards and transitions:

$$\hat{r}_k(s, a) := \frac{1}{N_k(s, a)} \sum_{t=1}^{t_k-1} \mathbb{1}\{s_t, a_t = s, a\} \cdot r_t \quad \text{and} \quad \hat{p}_k(s'|s, a) := \frac{1}{N_k(s, a)} \sum_{t=1}^{t_k-1} \mathbb{1}\{s_t, a_t, s_{t+1} = s, a, s'\}$$

where  $t_k$  is the starting time of episode  $k$ . The estimated transition probability  $\widehat{p}_k(s'|s, a)$  correspond to the sample mean of i.i.d. Bernoulli r.v. with mean  $p(s'|s, a)$  and therefore the population variance can be easily computed as  $\widehat{\sigma}_{p,k}^2(s'|s, a) := \widehat{p}_k(s'|s, a) (1 - \widehat{p}_k(s'|s, a))$ . The population variance of the reward can be computed recursively at the end of every episode:

$$\begin{aligned}\widehat{\sigma}_{r,k+1}^2(s, a) &:= \frac{1}{N_{k+1}^+(s, a)} \left( \sum_{l=1}^k S_l(s, a) \right) - (\widehat{r}_{k+1}(s, a))^2 \\ &= \frac{S_k(s, a)}{N_{k+1}^+(s, a)} + \frac{N_k(s, a)}{N_{k+1}^+(s, a)} \left( \widehat{\sigma}_{r,k}^2(s, a) + (\widehat{r}_k(s, a))^2 \right) - (\widehat{r}_{k+1}(s, a))^2.\end{aligned}$$

where  $S_k(s, a) := \sum_{t=1}^{t_k-1} \mathbb{1}\{s_t, a_t = s, a\} \cdot r_t^2$ . The extended MDP  $\mathcal{M}_k$  is defined by the compact sets

$$B_p^k(s, a, s') := \left[ \widehat{p}_k(s'|s, a) - \beta_{p,k}^{sas'}, \widehat{p}_k(s'|s, a) + \beta_{p,k}^{sas'} \right] \cap [0, 1] \quad (5)$$

$$B_r^k(s, a) := \left[ \widehat{r}_k(s, a) - \beta_{r,k}^{sa}, \widehat{r}_k(s, a) + \beta_{r,k}^{sa} \right] \cap [0, r_{\max}] \quad (6)$$

As UCRL2, UCRL2B executes a policy  $\pi_k$  which is an approximate solution to the following optimization problem:

$$g_k^* := \sup_{M' \in \mathcal{M}_k} \left\{ \max_{\pi \in \Pi^{\text{SD}}} g_{M'}^{\pi} \right\} = \sup_{M' \in \mathcal{M}_k} g_{M'}^* \quad (7)$$

Since  $M^* \in \mathcal{M}_k$  w.h.p., it holds that  $g_k^* \geq g_{M^*}^*$ . An approximated solution can be computed using Extended Value Iteration (EVI) (Jaksch et al., 2010). For technical reasons, we do not apply EVI directly to  $\mathcal{M}_k$  but to  $\mathcal{M}_\alpha^k$ , where  $\alpha$  is the coefficient of the aperiodicity transformation. EVI iteratively applies the following extended aperiodic optimal Bellman operator  $\mathcal{L}_\alpha^k$ :

$$\mathcal{L}_\alpha^k v(s) := \max_{a \in \mathcal{A}_s} \left\{ \max_{r \in B_r^k(s, a)} \{r\} + \alpha \cdot \max_{p \in B_p^k(s, a)} \{p^\top v\} \right\} + (1 - \alpha) \cdot v(s) \quad (8)$$

where  $B_p^k(s, a) := \{p \in \Delta_S : p(s') \in B_p^k(s, a, s'), \forall s' \in \mathcal{S}\}$  and  $\Delta_S$  is the  $S$ -dimensional simplex. We arbitrarily set  $\alpha = 0.9$ . We recall that, by properties of the aperiodicity transformation, the optimal gains of  $\mathcal{M}_\alpha^k$  and  $\mathcal{M}_k$  are equal (denoted by  $g_k^*$ ). If we ran EVI (see Alg. 2) on  $\mathcal{M}_\alpha^k$  with accuracy  $\epsilon_k = r_{\max}/t_k$ , we have that

$$|g_k - g_k^*| \leq \epsilon_k/2 := \frac{r_{\max}}{2t_k} \quad (9)$$

$$\text{and } \|\mathcal{L}_\alpha^k h_k - h_k - g_k e\|_\infty \leq \epsilon_k := \frac{r_{\max}}{t_k} \quad (10)$$

where  $(g_k, h_k, \pi_k) = \text{EVI}(\mathcal{L}_\alpha^k, \mathcal{G}_\alpha^k, \frac{r_{\max}}{t_k}, 0, s_1)$ .<sup>1</sup> We denote by  $r_k$  and  $p_k$  the optimistic reward and transitions at episode  $k$ .

**Regret Bound.** We can now provide the improved regret bound for UCRL2B

**Theorem 1.** *There exists a numerical constant  $\beta > 0$  such that for any communicating MDP, with probability at least  $1 - \delta$ , it holds that for all initial state distributions  $\mu_1 \in \Delta_S$  and for all time horizons  $T > 1$*

$$\begin{aligned}\Delta(\text{UCRL2B}, T) &\leq \beta \cdot r_{\max} \sqrt{D \left( \sum_{s,a} \Gamma(s, a) \right) T \ln \left( \frac{T}{\delta} \right) \ln(T)} \\ &\quad + \beta \cdot r_{\max} D^2 S^2 A \ln \left( \frac{T}{\delta} \right) \ln(T)\end{aligned} \quad (12)$$

<sup>1</sup>The extended greedy operator is defined as

$$\forall s \in \mathcal{S}, \forall v \in \mathbb{R}^S, \mathcal{G}_k v(s) \in \arg \max_{a \in \mathcal{A}_s} \left\{ \max_{r \in B_r^k(s, a)} r + \max_{p \in B_p^k(s, a)} p^\top v \right\}. \quad (11)$$

<p><b>Input:</b> Bellman operator <math>L : \mathbb{R}^S \mapsto \mathbb{R}^S</math>, greedy policy operator <math>G : \mathbb{R}^S \mapsto D^{\text{MR}}</math>, accuracy <math>\varepsilon \in ]0, r_{\max}[</math>, initial vector <math>v_0 \in \mathbb{R}^S</math>, arbitrary reference state <math>\bar{s} \in S</math></p> <p><b>Initialization:</b> <math>n = 0, v_1 = Lv_0</math></p> <p><b>While</b> <math>sp(v_{n+1} - v_n) &gt; \varepsilon</math> <b>do</b></p> <ol style="list-style-type: none"> <li>1. Increment <math>n \leftarrow n + 1</math></li> <li>2. Shift <math>v_n \leftarrow v_n - v_n(\bar{s})e</math></li> <li>3. <math>(v_{n+1}, d_n) := (Lv_n, Gv_n)</math></li> </ol> <p>Set <math>g := \frac{1}{2} \left( \max\{v_{n+1} - v_n\} + \min\{v_{n+1} - v_n\} \right)</math>, <math>h := v_n</math> and <math>\pi := (d_n)^\infty</math></p> <p><b>Return</b> gain <math>g</math>, bias <math>h</math>, policy <math>\pi</math></p>
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Figure 2: (Relative) Value Iteration.

Jaksch et al. (2010) showed that up to a multiplicative numerical constant, the regret of UCRL2 is bounded by  $r_{\max}DS\sqrt{AT \ln(T/\delta)}$ . After noticing that  $\sum_{s,a} \Gamma(s,a) \leq \Gamma SA$  we can simplify the bound in (12) as

$$\beta \cdot r_{\max} \sqrt{D\Gamma S A T \ln(T/\delta)} + \beta \cdot r_{\max} D^2 S^2 A \ln(T/\delta) \ln(T)$$

## 4 Improved regret analysis for UCRL2B

We now report the standard regret decomposition (e.g., Fruit et al., 2018). The regret after  $T$  time steps is defined as  $\Delta(\text{UCRL2B}, T) = \sum_{t=1}^T (g^* - r_t)$ . To begin with, we replace  $r_t$  by its expected value *conditioned* on the current state  $s_t$  using a martingale argument. Let's denote by  $\nu_k(s) := \sum_{a \in \mathcal{A}_s} \nu_k(s, a)$  the total number of visits in state  $s$  during episode  $k$ . Defining  $\Delta_k := \sum_{s \in \mathcal{S}} \nu_k(s) \left( g^* - \sum_{a \in \mathcal{A}_{s_t}} \pi_k(a|s) r(s, a) \right)$  the pseudo-regret of episode  $k$ , it holds with probability at least  $1 - \frac{\delta}{6}$  that for all  $T \geq 1$ :

$$\begin{aligned} R(T, \text{UCRL2B}) &\leq \sum_{k=1}^{k_T} \sum_s \nu_k(s) \left( g_{M^*}^* - \sum_a \pi_k(s, a) r(s, a) \right) + 2r_{\max} \sqrt{T \ln \left( \frac{5T}{\delta} \right)} \\ &= \sum_{k=1}^{k_T} \Delta_k + 2r_{\max} \sqrt{T \ln \left( \frac{5T}{\delta} \right)} \end{aligned}$$

where  $k_T = \sup\{k \geq 1 : t \geq t_k\}$ . By using optimism and the Bellman equation, we further decompose  $\Delta_k$  as (see e.g., Fruit et al., 2018; Fruit, 2019, for more details)

$$\Delta_k \leq \Delta_k^p + \Delta_k^r + \frac{3\varepsilon_k}{2} \sum_{s \in \mathcal{S}} \nu_k(s)$$

with

$$\begin{aligned} \Delta_k^p &= \alpha \underbrace{\sum_{s, a, s'} \nu_k(s) \pi_k(s, a) \left( p_k(s'|s, a) - p(s'|s, a) \right) h_k(s')}_{:= \Delta_k^{p1}} \\ &\quad + \alpha \underbrace{\sum_s \nu_k(s) \left( \sum_{a, s'} \pi_k(s, a) p(s'|s, a) h_k(s') - h_k(s) \right)}_{:= \Delta_k^{p2}} \end{aligned} \tag{13}$$

where  $\alpha \in ]0, 1]$  is the coefficient of the *aperiodicity transformation* applied to extended MDP  $\mathcal{M}_k$  (in most cases, this coefficient can be taken equal to 1 but we include it for the sake of generality) and  $p_k$  is the optimistic kernel at episode  $k$ . We also consider the general case where the optimistic policy  $\pi_k$  can be *stochastic* (in most cases this is not necessary).

We define the event  $E^C = \{\exists T > 0, \exists k > 0, s.t. M^* \notin \mathcal{M}_k\}$ . We recall that the probability of this event is small, see App. B.2:

$$\mathbb{P}(E^C) \leq \frac{\delta}{3}$$

#### 4.1 From $D$ to $\sqrt{D}$ : Variance Reduction Method

We will now prove Thm. 1. In order to improve the dependency of the regret bound in  $D$  (i.e., replace  $D$  by  $\sqrt{D}$ ), we refine our analysis with three key improvements:

1. We leverage on *Freedman's inequality* (Freedman, 1975) instead of Azuma's inequality to bound the MDS. We recall this inequality in Prop. 2 below.
2. We use a *tighter bound* than Hölder's inequality to upper-bound the sum  $\sum_{k=1}^{k_T} \Delta_k^{p3}$ .
3. We shift the optimistic bias  $h_{k_t}$  by a different constant *at every time step*  $t \geq 1$  rather than only at every episode  $k \geq 1$ . More precisely, the optimistic bias is shifted by a different constant for every episode  $k \geq 1$  and for every visited state  $s \in \mathcal{S}$ .

To the best of our knowledge, Thm. 1 and its proof are new although it is largely inspired by what is often referred to as "*variance reduction methods*" in the literature (Munos and Moore, 1999; Lattimore and Hutter, 2012, 2014; Azar et al., 2017). Similar techniques are used by (Azar et al., 2017) to achieve a similar bound but in the *finite horizon setting*. This approach is also related to (Talebi and Maillard, 2018) and (Maillard et al., 2014) (in the latter, the variance is called the distribution-norm instead of the variance).

**Proposition 2** (Freedman's inequality). *Let  $(X_n, \mathcal{F}_n)_{n \in \mathbb{N}}$  be an MDS such that  $|X_n| \leq a$  a.s. for all  $n \in \mathbb{N}$ . Then for all  $\delta \in ]0, 1[$ ,*

$$\mathbb{P} \left( \forall n \geq 1, \left| \sum_{i=1}^n X_i \right| \leq 2 \sqrt{\left( \sum_{i=1}^n \mathbb{V}(X_i | \mathcal{F}_{i-1}) \right) \cdot \ln \left( \frac{4n}{\delta} \right) + 4a \ln \left( \frac{4n}{\delta} \right)} \right) \geq 1 - \delta$$

For any vector  $u \in \mathbb{R}^S$ , we slightly abuse notation and write  $u^2 := u \circ u$  the *Hadamard product* of  $u$  with itself. For any probability distribution  $p$  over states  $\mathcal{S}$  and any vector  $u \in \mathbb{R}^S$  we define

$$\mathbb{V}_p(u) := p^\top u^2 - (p^\top u)^2 = \mathbb{E}_{X \sim p}[u(X)^2] - (\mathbb{E}_{X \sim p}[u(X)])^2$$

the "*variance*" of  $u$  with respect to  $p$ . For the sake of clarity we introduce new notations for the transition probabilities:  $p_k(s'|s) := \sum_{a \in \mathcal{A}_s} \pi_k(s, a) p_k(s'|s, a)$ ,  $\bar{p}_k(s'|s) := \sum_{a \in \mathcal{A}_s} \pi_k(s, a) p(s'|s, a)$  and  $\hat{p}_k(s'|s) := \sum_{a \in \mathcal{A}_s} \pi_k(s, a) \hat{p}_k(s'|s, a)$ , for every  $s, s' \in \mathcal{S}$  and every  $k \geq 1$ .

We start with a new bound relating  $\Delta_k^{p1}$ . We define  $\Delta_k^{p3} := \alpha \sum_{s, a, s'} \nu_k(s, a) (p_k(s'|s, a) - p(s'|s, a)) h_k(s')$ .

**Lemma 3.** *Under event  $E$ , with probability at least  $1 - \frac{\delta}{6}$ :*

$$\begin{aligned} \forall T \geq 1, \sum_{k=1}^{k_T} \Delta_k^{p1} &\leq \sum_{k=1}^{k_T} \Delta_k^{p3} + 4r_{\max} D \ln \left( \frac{24T}{\delta} \right) \\ &\quad + 2 \sqrt{S \ln \left( \frac{24T}{\delta} \right)} \left( \sqrt{\sum_{t=1}^T \mathbb{V}_{p_{k_t}(\cdot|s_t)}(\alpha h_{k_t})} + \sqrt{\sum_{t=1}^T \mathbb{V}_{\bar{p}_{k_t}(\cdot|s_t)}(\alpha h_{k_t})} \right) \end{aligned} \quad (14)$$

*Proof.* We use a martingale argument and Prop. 2 (Fruit, 2019, see).  $\square$

We *refine* the upper-bound of  $\Delta_k^{p3}$  derived by Jaksch et al. (2010). Instead of bounding the scalar product  $(p_k(\cdot|s, a) - p(\cdot|s, a))^\top w_k$  by  $\|p_k(\cdot|s, a) - p(\cdot|s, a)\|_1^\top \|w_k\|_\infty$  using Hölder's inequality, we bound it by  $\sum_{s'} |p_k(s'|s, a) - p(s'|s, a)| \cdot |w_k(s')|$  using the triangle inequality. Since  $\sum_{a, s'} p_k(s'|s, a) = \sum_{a, s'} p(s'|s, a) = 1$  we can shift  $h_k$  by an arbitrary scalar  $\lambda_k^s \in \mathbb{R}$  for all  $k \geq 1$  and all  $s \in \mathcal{S}$ , i.e.,  $w_k^s := h_k + \lambda_k^s e$ . Unlike in UCRL2, we choose a *state-dependent* shift, namely  $\lambda_k^s := -\sum_{a, s'} \hat{p}_k(s'|s, a) \pi_k(s, a) h_k(s') = -\hat{p}_k(\cdot|s)^\top h_k$ . It is easy to see that  $sp(w_k^s) = sp(h_k)$  and  $\|w_k^s\|_\infty \leq sp(h_k)$  implying that under event  $E$ ,  $\|w_k^s\|_\infty \leq (r_{\max} D)/\alpha$ .

Using the triangle inequality and the fact that  $p_k(s, a) \in B_p^k(s, a)$  by construction and  $p(s, a) \in B_p^k(s, a)$  under event  $E$ :

$$|p_k(s'|s, a) - p(s'|s, a)| \leq |p_k(s'|s, a) - \hat{p}_k(s'|s, a)| + |\hat{p}_k(s'|s, a) - p(s'|s, a)| \leq 2\beta_{p,k}^{sas'}$$

As a result we can write:

$$\begin{aligned}
\Delta_k^{p3} &\leq \alpha \sum_{k=1}^{k_T} \sum_{s,a,s'} \nu_k(s,a) \left| p_k(s'|s,a) - p(s'|s,a) \right| \cdot |w_k^s(s')| \\
&\leq 2\alpha \sum_{k=1}^{k_T} \sum_{s,a} \nu_k(s,a) \sum_{s'} \beta_{p,k}^{sa s'} \cdot |w_k^s(s')| \\
&= 4\alpha \sum_{k=1}^{k_T} \sum_{s,a} \nu_k(s,a) \left[ \sqrt{\frac{\ln(6SAT/\delta)}{N_k^+(s,a)}} \sum_{s' \in \mathcal{S}} \sqrt{\widehat{p}_k(s'|s,a)(1-\widehat{p}_k(s'|s,a))} w_k^s(s')^2 \right. \\
&\quad \left. + \frac{3 \ln(6SAT/\delta)}{N_k^+(s,a)} \sum_{s'} \underbrace{|w_k^{sa}(s')|}_{\leq (r_{\max} D)/\alpha} \right]
\end{aligned}$$

We denote by  $V_k(s,a) := \alpha^2 \sum_{s'} \widehat{p}_k(s'|s,a) w_k^s(s')^2$ . We can prove the following inequality:

**Lemma 4.** *It holds almost surely that for all  $k \geq 1$  and for all  $(s,a,s') \in \mathcal{S} \times \mathcal{A} \times \mathcal{S}$ :*

$$\alpha \sum_{s' \in \mathcal{S}} \sqrt{\widehat{p}_k(s'|s,a)(1-\widehat{p}_k(s'|s,a))} w_k^s(s')^2 \leq \sqrt{V_k(s,a) \cdot (\Gamma(s,a) - 1)} \quad (15)$$

*Proof.* Define  $\mathcal{S}_k(s,a) = \{s' \in \mathcal{S} : \widehat{p}_k(s'|s,a) > 0\}$ . Then, using Cauchy-Schartz inequality we have

$$\begin{aligned}
\sum_{s' \in \mathcal{S}} \sqrt{\widehat{p}_k(s'|s,a)(1-\widehat{p}_k(s'|s,a))} w_k^s(s')^2 &= \sum_{s' \in \mathcal{S}_k(s,a)} \sqrt{\widehat{p}_k(s'|s,a)(1-\widehat{p}_k(s'|s,a))} w_k^s(s')^2 \\
&\leq \sqrt{\left( \sum_{s' \in \mathcal{S}_k(s,a)} 1 - \widehat{p}_k(s'|s,a) \right) \cdot \left( \sum_{s' \in \mathcal{S}_k(s,a)} \widehat{p}_k(s'|s,a) w_k^s(s')^2 \right)} \\
&= \sqrt{\left( \Gamma_k(s,a) - 1 \right) \cdot \left( \sum_{s' \in \mathcal{S}} \widehat{p}_k(s'|s,a) w_k^s(s')^2 \right)} \leq \sqrt{\Gamma(s,a) \sum_{s' \in \mathcal{S}} \widehat{p}_k(s'|s,a) w_k^s(s')^2}
\end{aligned}$$

By definition, for all  $s' \in \mathcal{S}$ ,  $w_k(s') = h_k(s') - \mathbb{E}_{X \sim \widehat{p}_k(\cdot|s,a)}[h_k(X)]$  and so

$$\sum_{s' \in \mathcal{S}} \widehat{p}_k(s'|s,a) w_k^s(s')^2 = \mathbb{V}_{\widehat{p}_k(\cdot|s,a)}(h_k)$$

□

As a consequence of Lem. 4,

$$\begin{aligned}
\sum_{k=1}^{k_T} \Delta_k^{p3} &\leq 4 \sum_{k=1}^{k_T} \sum_{s,a} \nu_k(s,a) \left[ \sqrt{V_k(s,a) \frac{\Gamma(s,a)}{N_k^+(s,a)} \ln\left(\frac{6SAT}{\delta}\right)} + \frac{3r_{\max} DS}{N_k^+(s,a)} \ln\left(\frac{6SAT}{\delta}\right) \right] \\
&= 4 \sum_{k=1}^{k_T} \sum_{t=t_k}^{t_{k+1}-1} \left[ \sqrt{V_k(s_t, a_t) \frac{\Gamma(s_t, a_t)}{N_k^+(s_t, a_t)} \ln\left(\frac{6SAT}{\delta}\right)} + \frac{3r_{\max} DS}{N_k^+(s_t, a_t)} \ln\left(\frac{6SAT}{\delta}\right) \right]
\end{aligned}$$

Applying Cauchy-Schwartz gives

$$\begin{aligned}
\sum_{k=1}^{k_T} \sum_{t=t_k}^{t_{k+1}-1} \sqrt{V_k(s_t, a_t)} \sqrt{\frac{\Gamma(s_t, a_t)}{N_k^+(s_t, a_t)}} &\leq \sqrt{\sum_{k=1}^{k_T} \sum_{t=t_k}^{t_{k+1}-1} \frac{\Gamma(s_t, a_t)}{N_k^+(s_t, a_t)} \sum_{k=1}^{k_T} \sum_{t=t_k}^{t_{k+1}-1} V_k(s_t, a_t)} \\
&= \sqrt{\sum_{k=1}^{k_T} \sum_{s,a} \frac{\Gamma(s,a) \nu_k(s,a)}{N_k^+(s,a)} \sum_{t=1}^T V_{k_t}(s_t, a_t)}
\end{aligned}$$

Using Lem. 8, Jensen's inequality and the fact that  $N_{k_T+1}^+(s, a) \leq T$ , we can bound the first sum

$$\begin{aligned} \sum_{s,a} \sum_{k=1}^{k_T} \frac{\Gamma(s, a) \nu_k(s, a)}{N_k^+(s, a)} &\leq 2 \sum_{s,a} \Gamma(s, a) (1 + \ln(N_{k_T+1}^+(s, a))) \\ &\leq 2 \left( 1 + \ln \left( \frac{\sum_{s,a} \Gamma(s, a) N_{k_T+1}^+(s, a)}{\sum_{s,a} \Gamma(s, a)} \right) \right) \sum_{s,a} \Gamma(s, a) \\ &\leq 2(1 + \ln(T)) \sum_{s,a} \Gamma(s, a) \end{aligned}$$

To bound the second sum  $\sum_{t=1}^T V_{k_t}(s_t, a_t)$ , we rely on the following Lemma:

**Lemma 5.** *Under event  $E$ , with probability at least  $1 - \frac{\delta}{6}$ :*

$$\forall T \geq 1, \quad \sum_{t=1}^T V_{k_t}(s_t, a_t) \leq \sum_{t=1}^T \mathbb{V}_{\hat{p}_{k_t}(\cdot|s_t)}(\alpha h_{k_t}) + (r_{\max} D)^2 \sqrt{2T \ln \left( \frac{T}{\delta} \right)} \quad (16)$$

*Proof.* We notice that for all  $k \geq 1$  and  $s \in \mathcal{S}$ ,  $\sum_a \pi_k(s, a) V_k(s, a) = \mathbb{V}_{\hat{p}_k(\cdot|s)}(\alpha h_k)$ . The concentration inequality then follows from a martingale argument and Azuma's inequality.  $\square$

From Lem. 5 it follows that

$$\begin{aligned} \sum_{k=1}^{k_T} \Delta_k^{p3} &\leq 4 \sqrt{2 \left( 1 + \ln(T) \right) \ln \left( \frac{6SAT}{\delta} \right) \left( \sum_{s,a} \Gamma(s, a) \right) \left( (r_{\max} D)^2 \sqrt{2T \ln \left( \frac{T}{\delta} \right)} + \sum_{t=1}^T \mathbb{V}_{\hat{p}_{k_t}(\cdot|s_t)}(\alpha h_{k_t}) \right)} \\ &\quad + 24r_{\max} D S^2 A \ln \left( \frac{6SAT}{\delta} \right) (1 + \ln(T)) \end{aligned} \quad (17)$$

It now remains to bound  $\sum_{k=1}^{k_T} \Delta_k^{p2}$ . As shown by (Jaksch et al., 2010; Fruit et al., 2018) using telescopic sum argument:  $\sum_{k=1}^{k_T} \Delta_k^{p2} \leq \sum_{k=1}^{k_T} \Delta_k^{p4} + (r_{\max} D) k_T$  where

$$\Delta_k^{p4} = \alpha \sum_{t=t_k}^{t_{k+1}-1} \left( \sum_{a,s'} \pi_k(s_t, a) p(s'|s, a) w_k(s') - w_k(s_{t+1}) \right)$$

We bound  $\sum_{k=1}^{k_T} \Delta_k^{p4}$  using Freedman's inequality instead of Azuma's.

**Lemma 6.** *Under event  $E$ , with probability at least  $1 - \frac{\delta}{6}$ :*

$$\forall T \geq 1, \quad \sum_{k=1}^{k_T} \Delta_k^{p4} \leq 2 \sqrt{\left( \sum_{t=1}^T \mathbb{V}_{\bar{p}_{k_t}(\cdot|s_t)}(\alpha h_{k_t}) \right) \cdot \ln \left( \frac{24T}{\delta} \right)} + 4r_{\max} D \ln \left( \frac{24T}{\delta} \right) \quad (18)$$

*Proof.* We use a martingale argument and Prop. 2 (see App. B.1 for further details).  $\square$

## 4.2 From $D$ to $\sqrt{D}$ : Bounding the sum of variances

The main terms appearing respectively in (14), (17) and (18) all have the form of a *sum of variances over time*  $\sum_{t=1}^T \mathbb{V}_{p_t}(\alpha h_{k_t})$  with  $p_t$  a distribution over states (respectively  $p_{k_t}(\cdot|s_t)$ ,  $\bar{p}_{k_t}(\cdot|s_t)$  and  $\hat{p}_{k_t}(\cdot|s_t)$ )<sup>2</sup>, and  $h_{k_t}$  the optimistic bias of episode  $k_t$ . A first *naïve* upper bound of this sum can be derived using Popoviciu's inequality that we recall in Prop. 7.

**Proposition 7** (Popoviciu's inequality on variances). *Let  $M$  and  $m$  be upper and lower bounds on the values of a random variable  $X$  i.e.,  $\mathbb{P}m \leq X \leq M = 1$ . Then  $\mathbb{V}(X) \leq \frac{1}{4}(M - m)$ .*

<sup>2</sup>Recall that  $\bar{p}_k(\cdot|s) := \sum_a \pi_k(s, a) p(s'|s, a)$ .

Using Popoviciu's inequality and under event  $E$ ,

$$\mathbb{V}_{p_t}(\alpha h_{k_t}) \leq sp(\alpha h_k)^2/4 = \alpha^2 sp(h_k)^2/4 \leq (r_{\max}D)^2/4$$

and so  $\sum_{t=1}^T \mathbb{V}_{p_t}(\alpha h_{k_t}) \leq (r_{\max}D)^2 T/4$ . Unfortunately, this would result in a regret bound scaling as  $\tilde{\mathcal{O}}(r_{\max}D\sqrt{T})$  (ignoring all other terms like  $S$ ,  $A$ , logarithmic terms, etc.) which is *not better* than the classical bound of UCRL2. In this section, we show that the cumulative sum of variances only scales as  $\tilde{\mathcal{O}}(r_{\max}^2 DT + (r_{\max}D)^2\sqrt{T})$  resulting in a regret bound of order  $\tilde{\mathcal{O}}(r_{\max}\sqrt{DT} + r_{\max}DT^{1/4})$  (ignoring all other terms).

We start by analyzing the variance term  $\mathbb{V}_{\hat{p}_k(\cdot|s_t)}(\alpha h_k)$ . We will proceed similarly with the other variance terms  $\mathbb{V}_{p_k(\cdot|s_t)}(\alpha h_k)$  and  $\mathbb{V}_{\bar{p}_k(\cdot|s_t)}(\alpha h_k)$ . We do the following decomposition:

$$\begin{aligned} \mathbb{V}_{\hat{p}_k(\cdot|s_t)}(\alpha h_k) &= \alpha^2 \left( \hat{p}_k(\cdot|s_t)^\top h_k^2 - (\hat{p}_k(\cdot|s_t)^\top h_k)^2 \right) \\ &= \alpha^2 \left( \underbrace{(\hat{p}_k(\cdot|s_t) - \bar{p}_k(\cdot|s_t))^\top h_k^2}_{\textcircled{1}} + \underbrace{\bar{p}_k(\cdot|s_t)^\top h_k^2 - h_k^2(s_{t+1})}_{\textcircled{2}} + \underbrace{h_k^2(s_{t+1}) - (\hat{p}_k(\cdot|s_t)^\top h_k)^2}_{\textcircled{3}} \right) \end{aligned}$$

Notice that for any r.v.  $X$  and any scalar  $a \in \mathbb{R}$ ,  $\mathbb{V}(X+a) = \mathbb{V}(X)$ . Thus, the term  $\mathbb{V}_{\hat{p}_k(\cdot|s_t)}(\alpha h_k)$  remains unchanged when  $h_k$  is shifted by an arbitrary constant vector i.e., when  $h_k$  is replaced by  $w_k := h_k + \lambda_k e$ . As in UCRL2, we minimize the  $\ell_\infty$ -norm of  $w_k$  by choosing  $\lambda_k = -\frac{1}{2}(\max_{s \in \mathcal{S}}\{h_k(s)\} + \min_{s \in \mathcal{S}}\{h_k(s)\})$ . We recall that under event  $E$ ,  $\|w_k\|_\infty \leq (r_{\max}D)/(2\alpha)$  and so  $\|w_k^2\|_\infty \leq (r_{\max}D)^2/(4\alpha^2)$ .

① The *first term*  $\alpha^2 \sum_{k=1}^{k_T} \sum_{t=t_k}^{t_{k+1}-1} (\hat{p}_k(\cdot|s_t) - \bar{p}_k(\cdot|s_t))^\top w_k^2$  is similar to  $\sum_{k=1}^{k_T} \Delta_k^{p1}$  except that  $\alpha w_k$  is replaced by  $\alpha^2 w_k^2$  and  $p_k(\cdot|s_t)$  is replaced by  $\hat{p}_k(\cdot|s_t)$ . In the regret proof of UCRL2 we need to decompose  $p_k(\cdot|s_t) - \bar{p}_k(\cdot|s_t)$  into the sum of  $p_k(\cdot|s_t) - \hat{p}_k(\cdot|s_t)$  and  $\hat{p}_k(\cdot|s_t) - \bar{p}_k(\cdot|s_t)$ . Here we no longer need this decomposition and we can use the same derivation with  $sp(\alpha^2 w_k^2) \leq (r_{\max}D)^2/4$  instead of  $(r_{\max}D)/2$ . Therefore, with probability at least  $1 - \frac{\delta}{6}$  (and under event  $E$ ):

$$\begin{aligned} \alpha^2 \sum_{k=1}^{k_T} \sum_{t=t_k}^{t_{k+1}-1} (\hat{p}_k(\cdot|s_t) - \bar{p}_k(\cdot|s_t))^\top w_k^2 &\leq \frac{3}{2}(r_{\max}D)^2 \sqrt{\left( \sum_{s,a} \Gamma(s,a) \right) T \ln \left( \frac{6SAT}{\delta} \right)} \\ &\quad + (r_{\max}D)^2 \sqrt{T \ln \left( \frac{5T}{\delta} \right)} + 3(r_{\max}D)^2 S^2 A \ln \left( \frac{6SAT}{\delta} \right) (1 + \ln(T)) \end{aligned}$$

② The *second term*  $\alpha^2 \sum_{k=1}^{k_T} \sum_{t=t_k}^{t_{k+1}-1} \bar{p}_k(\cdot|s_t)^\top w_k^2 - w_k^2(s_{t+1})$  is identical to  $\sum_{k=1}^{k_T} \Delta_k^{p4}$  except that  $\alpha w_k$  is replaced by  $\alpha^2 w_k^2$ . With probability at least  $1 - \frac{\delta}{6}$  (and under event  $E$ ):

$$\alpha^2 \sum_{k=1}^{k_T} \sum_{t=t_k}^{t_{k+1}-1} \bar{p}_k(\cdot|s_t)^\top w_k^2 - w_k^2(s_{t+1}) \leq \frac{(r_{\max}D)^2}{2} \sqrt{T \ln \left( \frac{5T}{\delta} \right)}$$

③ The *last term*  $\alpha^2 \sum_{k=1}^{k_T} \sum_{t=t_k}^{t_{k+1}-1} w_k^2(s_{t+1}) - (\hat{p}_k(\cdot|s_t)^\top w_k)^2$  is the *dominant* one and requires more work. Unlike the first two terms, it scales *linearly* with  $T$  (instead of  $\tilde{\mathcal{O}}(\sqrt{T})$ ). We first notice that  $\hat{p}_k(\cdot|s_t)^\top w_k = w_k(s_t) + \hat{p}_k(\cdot|s_t)^\top w_k - w_k(s_t)$ . Using the fact that  $(a+b)^2 = a^2 + b(2a+b)$  with  $a = w_k(s_t)$  and  $b = \hat{p}_k(\cdot|s_t)^\top w_k - w_k(s_t)$  (and therefore  $2a+b = w_k(s_t) + \hat{p}_k(\cdot|s_t)^\top w_k$ ) we obtain:

$$(\hat{p}_k(\cdot|s_t)^\top w_k)^2 = w_k^2(s_t) + (\hat{p}_k(\cdot|s_t)^\top w_k - w_k(s_t)) \cdot (w_k(s_t) + \hat{p}_k(\cdot|s_t)^\top w_k)$$

and so applying the *reverse triangle inequality*:

$$(\hat{p}_k(\cdot|s_t)^\top w_k)^2 \geq w_k^2(s_t) - |\hat{p}_k(\cdot|s_t)^\top w_k - w_k(s_t)| \cdot |w_k(s_t) + \hat{p}_k(\cdot|s_t)^\top w_k| \quad (19)$$

For all  $k \geq 1$  and  $s \in \mathcal{S}$ , we define  $r_k(s) := \sum_a \pi_k(s,a) r_k(s,a)$ . Using the (near-)optimality equation we can write:

$$|g_k - r_k(s_t) + \alpha(w_k(s_t) - p_k(\cdot|s_t)^\top w_k)| = |g_k - r_k(s_t) + \alpha(h_k(s_t) - p_k(\cdot|s_t)^\top h_k)| \leq \varepsilon_k$$



Moreover,  $\varepsilon_k = \frac{r_{\max}}{t_k} \leq r_{\max}$ . As a result, since  $\alpha > 0$ :

$$\begin{aligned} & \alpha |\widehat{p}_k(\cdot|s_t)^\top w_k - w_k(s_t)| \\ &= |g_k - r_k(s_t) + \alpha(w_k(s_t) - p_k(\cdot|s_t)^\top w_k) - g_k + r_k(s_t) + \alpha(p_k(\cdot|s_t) - \widehat{p}_k(\cdot|s_t))^\top w_k| \\ &\leq \underbrace{|g_k - r_k(s_t) + \alpha(w_k(s_t) - p_k(\cdot|s_t)^\top w_k)|}_{\leq r_{\max}} + \underbrace{|r_k(s_t) - g_k|}_{\leq r_{\max}} + \alpha |(p_k(\cdot|s_t) - \widehat{p}_k(\cdot|s_t))^\top w_k| \\ &\leq 2r_{\max} + \alpha |(p_k(\cdot|s_t) - \widehat{p}_k(\cdot|s_t))^\top w_k| \end{aligned}$$

It is also immediate to see that  $|w_k(s_t) + \widehat{p}_k(\cdot|s_t)^\top w_k| \leq 2\|w_k\|_\infty \leq (r_{\max}D)/\alpha$ . Plugging these inequalities into (19) and adding  $w_k^2(s_{t+1})$  we obtain:

$$\begin{aligned} \alpha^2 \left( w_k^2(s_{t+1}) - (\widehat{p}_k(\cdot|s_t)^\top w_k)^2 \right) &\leq (2r_{\max} + \alpha |(p_k(\cdot|s_t) - \widehat{p}_k(\cdot|s_t))^\top w_k|) (r_{\max}D) \\ &+ \alpha^2 (w_k^2(s_{t+1}) - w_k^2(s_t)) \end{aligned} \quad (20)$$

It is easy to bound the telescopic sum

$$\alpha^2 \sum_{t=t_k}^{t_{k+1}-1} w_k^2(s_{t+1}) - w_k^2(s_t) = \alpha^2 (w_k^2(s_{t_{k+1}}) - w_k^2(s_{t_k})) \leq \alpha^2 w_k^2(s_{t_{k+1}}) \leq (r_{\max}D)^2/4 \quad (21)$$

Finally, the sum  $\alpha \sum_{k=1}^{k_T} \sum_{t=t_k}^{t_{k+1}-1} |(p_k(\cdot|s_t) - \widehat{p}_k(\cdot|s_t))^\top w_k|$  can be bounded in the exact same way as  $\sum_{k=1}^{k_T} \Delta_k^{p1}$ . With probability at least  $1 - \frac{\delta}{6}$ :

$$\begin{aligned} \alpha \sum_{k=1}^{k_T} \sum_{t=t_k}^{t_{k+1}-1} |(p_k(\cdot|s_t) - \widehat{p}_k(\cdot|s_t))^\top w_k| &\leq 3r_{\max}D \sqrt{\left( \sum_{s,a} \Gamma(s,a) \right) T \ln \left( \frac{6SAT}{\delta} \right)} + 4r_{\max}D \sqrt{T \ln \left( \frac{5T}{\delta} \right)} \\ &+ 6r_{\max}DS^2A \ln \left( \frac{6SAT}{\delta} \right) (1 + \ln(T)) \end{aligned} \quad (22)$$

After gathering (21) and (22) into (20) we conclude that with probability at least  $1 - \frac{\delta}{6}$  (and under event  $E$ ):

$$\alpha^2 \sum_{k=1}^{k_T} \sum_{t=t_k}^{t_{k+1}-1} w_k^2(s_{t+1}) - (\widehat{p}_k(\cdot|s_t)^\top w_k)^2 \leq \underbrace{2r_{\max}^2 DT}_{\text{main term}} + \frac{k_T (r_{\max}D)^2}{4} + \tilde{O} \left( (r_{\max}D)^2 \sqrt{\left( \sum_{s,a} \Gamma(s,a) \right) T} \right)$$

In conclusion, there exists an *absolute* numerical constant  $\beta > 0$  (i.e., independent of the MDP instance) such that with probability at least  $1 - \frac{5\delta}{6}$ :

$$\sum_{t=1}^T \mathbb{V}_{\widehat{p}_{k_t}(\cdot|s_t)}(\alpha h_{k_t}) \leq \beta \cdot \left( r_{\max}^2 DT + (r_{\max}D)^2 \sqrt{\left( \sum_{s,a} \Gamma(s,a) \right) T \ln \left( \frac{T}{\delta} \right)} + (r_{\max}D)^2 S^2 A \ln \left( \frac{T}{\delta} \right) \ln(T) \right)$$

We can prove the same bound (possibly with a different multiplicative constant  $\beta$ ) for  $\sum_{t=1}^T \mathbb{V}_{\bar{p}_{k_t}(\cdot|s_t)}(\alpha h_{k_t})$  and  $\sum_{t=1}^T \mathbb{V}_{p_{k_t}(\cdot|s_t)}(\alpha h_{k_t})$  using the same derivation.

### 4.3 Completing the regret bound of Thm. 1

After plugging the bound derived for the sum of variances in the previous section (Sec. 4.2) into (14), (17) and (18), we notice that (14) and (18) can be upper-bounded by (17) *up to a multiplicative numerical constant* and so it is enough to restrict attention to (17). The dominant term that we obtain is (ignoring numerical constants):

$$r_{\max} \sqrt{\left( \sum_{s,a} \Gamma(s,a) \right) \ln \left( \frac{T}{\delta} \right) \ln(T) \left( DT + D^2 \sqrt{\left( \sum_{s,a} \Gamma(s,a) \right) T \ln \left( \frac{T}{\delta} \right)} + D^2 S^2 A \ln \left( \frac{T}{\delta} \right) \ln(T) \right)}$$

Using the fact that  $\sqrt{\sum_i a_i} \leq \sum_i \sqrt{a_i}$  for any  $a_i \geq 0$ , we can bound the above square-root term by three simpler terms:

- (1) A  $\sqrt{T}$ -term (dominant):  $r_{\max} \sqrt{D \left( \sum_{s,a} \Gamma(s, a) \right) T \ln \left( \frac{T}{\delta} \right) \ln(T)}$
- (2) A  $T^{1/4}$ -term:  $r_{\max} D \left( \sum_{s,a} \Gamma(s, a) \right)^{3/4} T^{1/4} \left( \ln \left( \frac{T}{\delta} \right) \right)^{3/4} \sqrt{\ln(T)}$
- (3) A logarithmic term:  $r_{\max} D \sqrt{S^2 A \left( \sum_{s,a} \Gamma(s, a) \right) \ln \left( \frac{T}{\delta} \right) \ln(T)} \leq r_{\max} D S^2 A \ln \left( \frac{T}{\delta} \right) \ln(T)$

When  $T \geq D^2 \left( \sum_{s,a} \Gamma(s, a) \right) \ln \left( \frac{T}{\delta} \right)$ , we notice that the  $T^{1/4}$ -term (2) is actually upper-bounded by the  $\sqrt{T}$ -term (1), while for  $T \leq D^2 \left( \sum_{s,a} \Gamma(s, a) \right) \ln \left( \frac{T}{\delta} \right)$  we can use the trivial upper-bound  $r_{\max} T$  on the regret:

$$R(T, M^*, \text{UCRL2B}) \leq r_{\max} T \leq r_{\max} D^2 \left( \sum_{s,a} \Gamma(s, a) \right) \ln \left( \frac{T}{\delta} \right) \leq r_{\max} D^2 S^2 A \ln \left( \frac{T}{\delta} \right)$$

To complete the regret bound of Thm. 1 we also need to take into consideration the *lower order terms* of (14), (17) and (18). It turns out that the only terms that are not already upper-bounded by (1), (2) and (3) (up to multiplicative numerical constants) sum as:

$$r_{\max} \sqrt{SAT \ln \left( \frac{T}{\delta} \right)} + r_{\max} SA \ln \left( \frac{T}{\delta} \right) \ln(T) + r_{\max} D^2 S^2 A \ln \left( \frac{T}{\delta} \right) \ln(T)$$

All the above logarithmic terms can be bounded by:  $\max \{r_{\max}, r_{\max} D^2\} S^2 A \ln \left( \frac{T}{\delta} \right) \ln(T)$ . Moreover, all the  $\sqrt{T}$ -terms can be bounded by

$$\max \{r_{\max}, r_{\max} \sqrt{D}\} \sqrt{\left( \sum_{s,a} \Gamma(s, a) \right) T \ln \left( \frac{T}{\delta} \right) \ln(T)}$$

To conclude, we only need to *adjust*  $\delta$  to obtain an event of probability at least  $1 - \delta$ . This will *only* impact the multiplicative numerical constants of the above terms.

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## A Additional Results

**Lemma 8.** *It holds almost surely that for all  $k \geq 1$  and for all  $(s, a) \in \mathcal{S} \times \mathcal{A} \times \mathcal{S}$ :*

$$\sum_{k=1}^{k_T} \frac{\nu_k(s, a)}{\sqrt{N_k^+(s, a)}} \leq 3\sqrt{N_{k_T+1}(s, a)} \quad \text{and} \quad \sum_{k=1}^{k_T} \frac{\nu_k(s, a)}{N_k^+(s, a)} \leq 2 + 2\ln(N_{k_T+1}^+(s, a)) \quad (23)$$

*Proof.* The proof follows from the rate of divergence of the series  $\sum_{i=1}^n \frac{1}{\sqrt{i}} \sim \sqrt{n}$  and  $\sum_{i=1}^n \frac{1}{i} \sim \ln(n)$  respectively when  $n \rightarrow +\infty$ .  $\square$

## B MDS

For any  $t \geq 0$ , the  $\sigma$ -algebra induced by the past history of state-action pairs and rewards up to time  $t$  (included) is denoted  $\mathcal{F}_t = \sigma(s_1, a_1, r_1, \dots, s_t, a_t, r_t, s_{t+1})$  where by convention  $\mathcal{F}_0 = \sigma(\emptyset)$  and  $\mathcal{F}_\infty := \cup_{t \geq 0} \mathcal{F}_t$ . Trivially, for all  $t \geq 0$ ,  $\mathcal{F}_t \subseteq \mathcal{F}_{t+1}$  and the filtration  $(\mathcal{F}_t)_{t \geq 0}$  is denoted by  $\mathbb{F}$ . We recall that  $k_t$  is the integer-valued r.v. indexing the current episode at time  $t$ . It is immediate from the termination condition of episodes that for all  $t \geq 1$ ,  $k_t$  is  $\mathcal{F}_{t-1}$ -measurable i.e., the past sequence  $(s_1, a_1, r_1, \dots, s_{t-1}, a_{t-1}, r_{t-1}, s_t)$  fully determines the ongoing episode at time  $t$ . As a consequence, the stationary (randomized) policy  $\pi_{k_t}$  executed at time  $t$  is also  $\mathcal{F}_{t-1}$ -measurable.

### B.1 Proof of Lemma 6

Let's define the stochastic process

$$X_t := \sum_{a, s'} \pi_{k_t}(s_t, a) p_{k_t}(s' | s_t, a) h_{k_t}(s') - \sum_{s'} p_{k_t}(s' | s_t, a_t) h_{k_t}(s')$$

Let's define  $\lambda_t = -\sum_{a, s'} \pi_{k_t}(s_t, a) p_{k_t}(s' | s_t, a) h_{k_t}(s')$  and  $w_t = h_{k_t} + \lambda_t e$ . Since by definition  $\sum_{s'} p_{k_t}(s' | s_t, a_t) = 1$ , we have

$$X_t = -\sum_{s'} p_{k_t}(s' | s_t, a_t) w_t(s')$$

It is easy to verify that  $\mathbb{E}[X_t | \mathcal{F}_{t-1}] = 0$  and so  $(X_t, \mathcal{F}_t)_{t \geq 1}$  is an MDS. Moreover,  $|X_t| \leq \|w_t\|_\infty \leq sp(h_{k_t}) \leq (r_{\max} D)$  and

$$\mathbb{V}(X_t | \mathcal{F}_{t-1}) = \sum_a \pi_{k_t}(s_t, a) \left( \sum_{s'} p_{k_t}(s' | s_t, a) w_t(s') \right)^2$$

**Proposition 9.** For any  $n \geq 1$  and any  $n$ -tuple  $(a_1, \dots, a_n) \in \mathbb{R}^n$ ,  $(\sum_{i=1}^n a_i)^2 \leq n (\sum_{i=1}^n a_i^2)$ .

*Proof.* The statement is trivially true for  $n = 1$ . For  $n = 2$  we have  $(a_1 - a_2)^2 = a_1^2 + a_2^2 - 2a_1a_2 \geq 0$  implying that  $2a_1a_2 \leq a_1^2 + a_2^2$ . Therefore,  $(a_1 + a_2)^2 = a_1^2 + a_2^2 + 2a_1a_2 \leq 2(a_1^2 + a_2^2)$  and so the result holds. We prove the result for  $n \geq 2$  by induction. Assumed that it is true for any  $n \geq 2$ . Then we have:

$$\begin{aligned} \left(\sum_{i=1}^{n+1} a_i\right)^2 &= \underbrace{\left(\sum_{i=1}^n a_i\right)^2}_{\leq n(\sum_{i=1}^n a_i^2)} + a_{n+1}^2 + 2a_{n+1} \sum_{i=1}^n a_i \\ &\leq n \left(\sum_{i=1}^n a_i^2\right) + a_{n+1}^2 + \sum_{i=1}^n \underbrace{2a_i a_{n+1}}_{\leq a_i^2 + a_{n+1}^2} \leq (n+1) \cdot \left(\sum_{i=1}^{n+1} a_i^2\right) \end{aligned}$$

where the first inequality follows from the induction hypothesis and the second inequality follows from the inequality for  $n = 2$  that we proved. This concludes the proof.  $\square$

For the sake of clarity we will now use the notation  $p_k(s'|s) := \sum_{a \in \mathcal{A}_s} \pi_k(s, a) p_k(s'|s, a)$  for every  $s, s' \in \mathcal{S}$  and every  $k \geq 1$ . Using Prop. 9 we have that

$$\begin{aligned} \mathbb{V}(X_t | \mathcal{F}_{t-1}) &\leq S \sum_{a, s'} \pi_{k_t}(s_t, a) \underbrace{p_{k_t}(s'|s_t, a)^2}_{\leq p_{k_t}(s'|s_t, a)} w_{k_t}(s')^2 \\ &\leq S \sum_{a, s'} \pi_{k_t}(s_t, a) p_{k_t}(s'|s_t, a) w_{k_t}(s')^2 = S \cdot \mathbb{V}_{p_{k_t}(\cdot|s_t)}(h_{k_t}) \end{aligned}$$

After applying Freedman's inequality (Prop. 2) to the MDS  $(X_t, \mathcal{F}_t)_{t \geq 1}$  we obtain that with probability at least  $1 - \frac{\delta}{6}$ , for all  $T \geq 1$ :

$$\begin{aligned} \sum_{k=1}^{k_T} \sum_{s, a, s'} \nu_k(s) \pi_k(s, a) p_k(s'|s, a) h_k(s') &\leq \sum_{k=1}^{k_T} \sum_{s, a, s'} \nu_k(s, a) p_k(s'|s, a) h_k(s') + 2(r_{\max} D) \ln \left( \frac{24T}{\delta} \right) \\ &\quad + 2 \sqrt{S \ln \left( \frac{24T}{\delta} \right) \sum_{t=1}^T \mathbb{V}_{p_{k_t}(\cdot|s_t)}(h_{k_t})} \end{aligned} \quad (24)$$

We can do exactly the same analysis with the stochastic process

$$X_t := \sum_{a, s'} \pi_{k_t}(s_t, a) p(s'|s_t, a) h_{k_t}(s') - \sum_{s'} p(s'|s_t, \mathbf{a}_t) h_{k_t}(s')$$

i.e., with  $p$  instead of  $p_{k_t}$  and we obtain that with probability at least  $1 - \frac{\delta}{6}$ , for all  $T \geq 1$ :

$$\begin{aligned} -\sum_{k=1}^{k_T} \sum_{s, a, s'} \nu_k(s) \pi_k(s, a) p(s'|s, a) h_k(s') &\leq -\sum_{k=1}^{k_T} \sum_{s, a, s'} \nu_k(s, a) p(s'|s, a) h_k(s') + 2(r_{\max} D) \ln \left( \frac{24T}{\delta} \right) \\ &\quad + 2 \sqrt{S \ln \left( \frac{24T}{\delta} \right) \sum_{t=1}^T \mathbb{V}_{\bar{p}_{k_t}(\cdot|s_t)}(h_{k_t})} \end{aligned} \quad (25)$$

with the notation  $\bar{p}_k(s'|s) := \sum_{a \in \mathcal{A}_s} \pi_k(s, a) p(s'|s, a)$  for every  $s, s' \in \mathcal{S}$  and  $k \geq 1$ .

## B.2 Definition of The Confidence Intervals

**Theorem 10.** The probability that there exists  $k \geq 1$  s.t. the true MDP  $M$  does not belong to the extended MDP  $\mathcal{M}_k$  defined by Eq. 5 and 6 is at most  $\frac{\delta}{3}$ , that is

$$\mathbb{P}(\exists k \geq 1, \text{ s.t. } M \notin \mathcal{M}_k) \leq \frac{\delta}{3}.$$

*Proof.* We want to bound the probability of event  $E := \bigcup_{k=1}^{+\infty} \{M \notin \mathcal{M}_k\}$ . As explained by Lattimore and Szepesvári (2018, Section 4.4), when  $(s, a)$  is visited for the  $n$ -th times, the reward that we observe is the  $n$ -th element of an infinite sequence of i.i.d. r.v. lying in  $[0, r_{\max}]$  with expected value  $r(s, a)$ . Similarly, the next state that we observe is the  $n$ -th element of an infinite sequence of i.i.d. r.v. lying in  $\mathcal{S}$  with probability density function (pdf)  $p(\cdot|s, a)$ . In UCRL2, we defined the sample means  $\hat{p}_k$  and  $\hat{r}_k$ , and the confidence intervals  $B_p^k$  and  $B_r^k$  (Eq. 5 and 6) as depending on  $k$ . Actually, this quantities depends only on the first  $N_k(s, a)$  elements of the infinite i.i.d. sequences that we just mentioned. For the rest of the proof, we will therefore slightly change our notations and denote by  $\hat{p}_n(s'|s, a)$ ,  $\hat{r}_n(s, a)$ ,  $B_p^n(s'|s, a)$  and  $B_r^n(s, a)$  the sample means and confidence intervals after the first  $n$  visits in  $(s, a)$ . Thus, the r.v. that we denoted by  $\hat{p}_k$  in UCRL2 actually corresponds to  $\hat{p}_{N_k(s, a)}$  with our new notation (and similarly for  $\hat{r}_k$ ,  $B_p^k$  and  $B_r^k$ ). This change of notation will make the proof easier.

$M \notin \mathcal{M}_k$  means that there exists  $k \geq 1$  s.t. either  $p(s'|s, a) \notin B_p^{N_k(s, a)}(s, a, s')$  or  $r(s, a) \notin B_r^{N_k(s, a)}(s, a)$  for at least one  $(s, a, s') \in \mathcal{S} \times \mathcal{A} \times \mathcal{S}$ . This means that there exists at least one value  $n \geq 0$  s.t. either  $p(s'|s, a) \notin B_p^n(s, a, s')$  or  $r(s, a) \notin B_r^n(s, a)$ . As a consequence we have the following inclusion

$$E \subseteq \bigcup_{s, a} \bigcup_{n=0}^{+\infty} \{r(s, a) \notin B_r^n(s, a)\} \cup \bigcup_{s'} \{p(s'|s, a) \notin B_p^n(s, a, s')\} \quad (26)$$

Using Boole's inequality we thus have:

$$\mathbb{P}(E) \leq \sum_{s, a} \sum_{n=0}^{+\infty} \left( \mathbb{P}(r(s, a) \notin B_r^n(s, a)) + \sum_{s'} \mathbb{P}(p(s'|s, a) \notin B_p^n(s, a, s')) \right) \quad (27)$$

Let's fix a 3-tuple  $(s, a, s') \in \mathcal{S} \times \mathcal{A} \times \mathcal{S}$  and define for all  $n \geq 0$

$$\epsilon_{p, n}^{sas'} := \hat{\sigma}_{p, n}(s'|s, a) \sqrt{\frac{2 \ln(30S^2A(n^+)^2/\delta)}{n^+}} + \frac{3 \ln(30S^2A(n^+)^2/\delta)}{n^+} \quad (28)$$

$$\epsilon_{r, n}^{sa} := \hat{\sigma}_{r, n}(s, a) \sqrt{\frac{2 \ln(30SA(n^+)^2/\delta)}{n^+}} + \frac{3r_{\max} \ln(30SA(n^+)^2/\delta)}{n^+} \quad (29)$$

where  $\hat{\sigma}_{p, n}(s'|s, a)$  and  $\hat{\sigma}_{r, n}(s, a)$  denote the population variances obtained with the first  $n$  samples. It is immediate to verify that  $\epsilon_{p, n}^{sas'} \leq \beta_{p, n}^{sas'}$  and  $\epsilon_{r, n}^{sa} \leq \beta_{r, n}^{sa}$  a.s. (see Eq. 3 and 4 with  $N_k(s, a)$  replaced by  $n$ ). Using the empirical Bernstein inequality (Audibert et al., 2009, Thm. 1) we have that for all  $n \geq 1$ :

$$\mathbb{P}\left(|p(s'|s, a) - \hat{p}_n(s'|s, a)| \geq \beta_{p, n}^{sas'}\right) \leq \mathbb{P}\left(|p(s'|s, a) - \hat{p}_n(s'|s, a)| \geq \epsilon_{p, n}^{sas'}\right) \leq \frac{\delta}{10n^2S^2A} \quad (30)$$

$$\mathbb{P}\left(|r(s, a) - \hat{r}_n(s, a)| \geq \beta_{r, n}^{sa}\right) \leq \mathbb{P}\left(|r(s, a) - \hat{r}_n(s, a)| \geq \epsilon_{r, n}^{sa}\right) \leq \frac{\delta}{10n^2SA} \quad (31)$$

Note that when  $n = 0$  (i.e., when there hasn't been any observation of  $(s, a)$ ),  $\epsilon_{p, 0}^{sas'} \geq 1$  and  $\epsilon_{r, 0}^{sa} \geq r_{\max}$  so  $\mathbb{P}\left(|p(s'|s, a) - \hat{p}_0(s'|s, a)| \geq \epsilon_{p, 0}^{sas'}\right) = \mathbb{P}\left(|r(s, a) - \hat{r}_0(s, a)| \geq \epsilon_{r, 0}^{sa}\right) = 0$  by definition. Since in addition (also by definition)

$$B_p^n(s, a, s') \subseteq \left[\hat{p}_n(s'|s, a) - \beta_{p, n}^{sas'}, \hat{p}_n(s'|s, a) + \beta_{p, n}^{sas'}\right] \quad (\text{see Eq. 5})$$

and

$$B_r^n(s, a) \subseteq \left[\hat{r}_n(s, a) - \beta_{r, n}^{sa}, \hat{r}_n(s, a) + \beta_{r, n}^{sa}\right] \quad (\text{see Eq. 6})$$

we conclude that for all  $n \geq 1$

$$\mathbb{P}(p(s'|s, a) \notin B_p^n(s, a, s')) \leq \frac{\delta}{10n^2S^2A} \quad \text{and} \quad \mathbb{P}(r(s, a) \notin B_r^n(s, a)) \leq \frac{\delta}{10n^2SA}$$

and these probabilities are equal to 0 if  $n = 0$ . Plugging these inequalities into Eq. (27) we obtain:

$$\mathbb{P}(\exists T \geq 1, \exists k \geq 1 \text{ s.t. } M \notin \mathcal{M}_k) \leq \sum_{s, a} \left(0 + \sum_{n=1}^{+\infty} \left(\frac{\delta}{10n^2SA} + \sum_{s'} \frac{\delta}{10n^2S^2A}\right)\right) = \frac{2\pi^2\delta}{60} \leq \frac{\delta}{3}$$

which concludes the proof.  $\square$